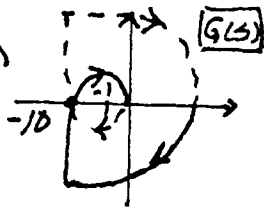
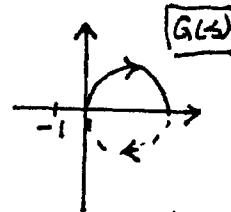


8.10. (a)



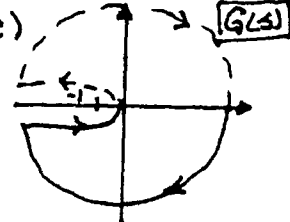
$$Z = N + P = 2; \therefore \text{unstable}$$

(b)



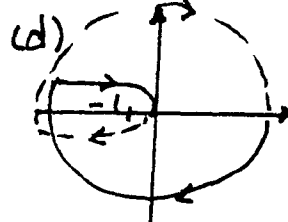
$$Z = N + P = 0; \therefore \text{stable}$$

(c)



$$Z = N + P = 0; \therefore \text{stable}$$

(d)



$$Z = N + P = 2 + 0 = 2; \therefore \text{unstable}$$

$$8.13. (a) G(j5.7) \approx 0.12 \angle -180^\circ; \therefore \text{gain margin} \approx \frac{1}{0.12} = 8.33$$

$$G(j1.5) \approx 1 \angle -100^\circ; \phi_m \approx 80^\circ$$

$$(b) 2.5 G(j5.7) \approx 0.30 \angle -180^\circ; \therefore \text{gain margin} \approx \frac{1}{0.3} = 3.33$$

$$2.5 G(j3) \approx 1 \angle -144^\circ; \therefore \phi_m \approx 36^\circ$$

$$(c) T(j1) = \frac{1.573 \angle -77.3^\circ}{1 + 1.573 \angle -77.3^\circ} = \frac{1.573 \angle -77.3^\circ}{2.042 \angle -48.8^\circ} = 3.85 \cos(t + 15^\circ)$$